

Title	仮想現実環境における衝突検出ハードウェアに関する研究
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Collision detection hardware in virtual reality environment

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Virtual reality is practical use with speedup of computers in recent years and it has come to be used in the industrial field. Application ranges are many. such as remote operation of robot, computer game, a medical simulation, are various. collision detection of box or sphere pair was researched by many researcher. but, collision detection of polygon pair in virtual reality environment was researched by few researcher. Reason is computational cost by collision detection of many polygon. computation cost reduced by bounding volume. Many researchers are reducing computational cost using bounding volume hierarchies. However, making bounding volume hierarchies takes many time. It is difficult collision detection of frequently deformable object. Therefore, we use boundary volume of little computational cost. but, it has many computational cost. Therefore, I research the intersection detection hardware of a triangular polygon.

1 approach

1.1 Improvement in throughput

- Implementation of high-speed throughput by pipelining
- Implementation of high-speed by cache memory

2 Result

intersection detection hardware of triangular polygon was described using VHDL. I have designed for the hardware which assumed FPGA on PCI-board (Virtex-II Pro XC2VP100 made in Xilinx corp).

2.1 Performance of hardware

- By 32 steps of pipelining, critical path is 9ns and maximum operating frequency is 111MHz.
- My hardware compared to software approaches is 79 times the processing speed.
- As compared with the processing speed of the bounding volume processing hardware using the visibility check function of GPU (graphics processing unit). My hardware was high-speed in less than the 800 polygon pair.

3 conclusion

The processing time of the triangular polygon intersection detection which becomes a bottleneck in a virtual reality environment was accelerated by designing hardware special.